CPSC 416 Distributed Systems

Winter 2022 Term 2 (January 24, 2023)

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Logistics



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Deadlines

Project 3 Released. Initially Due: February 13, 2023
Project 4 Released. Initially Due: March 13, 2023
Project 5 Released Due: April 13, 2023
Note: all project work is due April 13, 2023. Late projects have a 75% score cap.
Alternate Path 1 & 2: Initial Proposal due January 30, 2023.

Instructor Office Hours:

- Zoom Office Hours (Tuesday) @ 13:00-14:00
- Discord (Casual) Office Hours (Thursday) @ 14:00-15:00



Readings

Required:

Impossibility of Distributed Consensus with One Faulty Process

Recommended:

Two General's Problem



Questions?

Questions about the class?

Questions about the previous lecture?

Funny stories to share?



Today's Failure



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Types of Failures

Robert Vitillo's Blog (How distributed systems fail)

Single point of failure

- Non-replicated configuration database
- HTTPS
 - Manually renewed certificate = nobody can connect

Slow networks

- How long should we wait?
- What happens if we *don't* wait?

Slow Processes

• TCP connection exhaustion



Types of Failures

Demand spikes

- Failover = load spike
- Increased load = slow/no response
 - How long does a client wait?

Cascading failures

- Load spike
- Failed node resumes operation
- Working node collapses
- Repeat cycle



Lesson Goals



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Achieving Consensus

Define *consensus*

Distributed systems limits on reaching consensus

Fischer-Lynch-Patterson (FLP) Theorem

Practical consensus



What is consensus?

Agreement between distributed processes on shared state

- Value
- Action
- Timestamp
- Transaction outcome

Consensus allows a system to be correct



Challenges achieving consensus

Classic distributed systems problems

- Network behaviour
- No global clock
- Bad actors
 - Malicious
 - Broken behaviour
- Non-determinism

System Properties

All non-faulty processes eventually determine the value

All processes determine the same value

The value is one that was proposed by *at least one* process

• Not externally provided

Question: how can (or if) we achieve this?



System Model

Asynchronous

- Messages may be reordered
- Messages may be delayed
- Messages are *not* corrupted

Bad behaviour

• At most one faulty process

Fail-stop model:

• Same as message delay

Note: the real world is more complex.



Is consensus reachable?

Given our simple model:

- If not possible in *this* simple model, it won't work with:
 - Corrupted messages
 - Multiple bad actors
 - Byzantine failures
- If possible: try for more complex models



Terminology

Admissible run: run of our model system

- At most one faulty process
- Messages *eventually* delivered

Deciding run = admissible run where *some* non-faulty processes reach a decision

Consensus = all admissible runs are deciding runs

• A "totally correct" consensus protocol

Decisions:

- Uni-valent single value result
- Bi-valent two or more values result ("non-deciding")





In a system with one faulting process there is no correct consensus protocol.

This result is important because:

• True for *this* system

Question: Can we find a *different* (but viable) system that can have consensus?



Proof Sketch

Model System:

- Asynchronous communication
- One faulty process
- Fail-stop model

Question 1: Can we identify a configuration and run that do not reach a deciding state?

Question 2: Can we find at least one admissible schedule that is not a deciding schedule?

- Admissible schedule = "1 faulty process, all messages delivered"
- Deciding schedule = "system is in a bivalent configuration"



Proof walk-through

Start

- Nodes make a binary decision (true/false)
- One faulty node is *possible*
- Messages may be delayed or reordered (but *not* lost)



Lemma

B

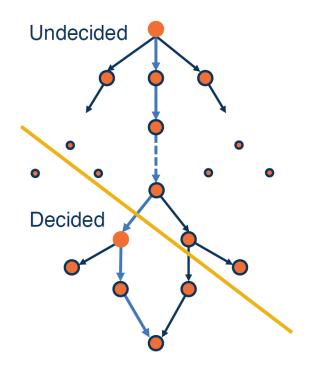
Assume:

- There is an *initial configuration*
- The final decision is not pre-determined
- Consensus is based upon *proposed* (not pre-determined) value
- The final decision depends on the event schedule

Conclusion:

• There *must exist* an initial bivalent configuration

FLP Proof (Lemma)



There must be:

- A bivalent state
- A step (message)
- That message must change the system to a *univalent* system

Why?

To be deciding, the system must reach a single decision = univalent.

Could be the *last* message.



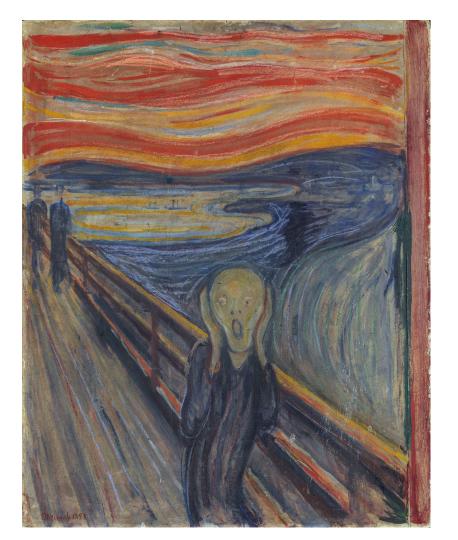
Lemma (FLP Theorem)

Recall:

- System allows delayed/reordered messages
- Permits at least one schedule that never becomes univalent

This means an admissible non-deciding schedule can exist







FLP Theorem: Putting it all together

System consists of nodes that decide true/false

Lemma:

- There is an initial configuration
- A non-predetermined final decision
- Final decision depends on the schedule of events
 - Must have an initial bivalent configuration
- Some message must cause system to become univalent
- Messages can be delayed/reordered to avoid that specific message

Recall: one faulty node is *possible*. Combine this...

An admissible non-deciding schedule can exist.





So... does that mean we can't reach consensus?

Real world:

- Faults are *inevitable*
- Network delays will happen
- Can't make a *stronger* useful model

Question:

How can we reach consensus?



Change the model



Change our assumptions

Change the system properties

Find situations where the protocol *does* decide.

• What are the conditions where it *will* provide consensus?

Consensus is possible

2 Phase Commit (2PC)

3 Phase Commit (asynchronous 2PC)

Paxos

Raft/Viewstamped Replication



Lesson Summary



Sec. Later

Consensus: harder than we thought

FLP Theorem proves

- Given a simple model
 - One faulting process
 - Reordering/delaying messages
- Cannot guarantee consensus

We need consensus

- We can change the "simple model"
- We have more work to do!



Questions?



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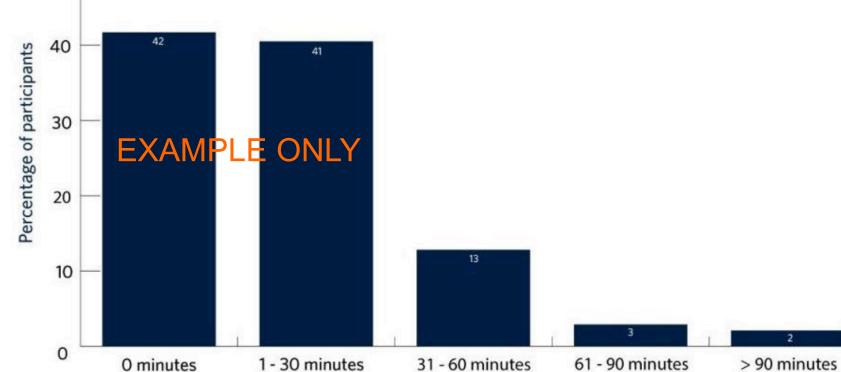


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